

The Automated Exploitation Grand Challenge

Tales of Weird Machines

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You are an inspiration for the Automated Exploitation Grand Challenge

Thank you

What is Automated Exploitation?

- The ability to generate a successful computer attack with reduced or entirely without human interaction.
- It is important to understand the hardness of AE to measure the risk on critical infrastructure and online properties.
- There are many domains of attack: network, web, kernel, system, hardware, applications. Our focus today is on **software security**.

What are Weird Machines?

- Weird Machine (WM): “The underlying capacity of a program to perform runtime computations that escape the program specification”
 - (1) If extra computations are consistent with the intended program specification, the WM can lead to a covert execution of code within the program.
 - (2) If extra computations violate the intended program specification, the WM can lead to a security exploit (what we will talk about today).

Today's exploits techniques

Modern history of exploit techniques :

- Code-reuse attacks: Computations without code injection
 - Started with “Return into Libc” (Solar Designer’s 1997)
 - Advanced by “Return into PLT” (Rafal Wojtczuk’s 1998)
 - Generalized by Chunk reuse (“borrowing”) technique (Richarte 2000, Kraemer 2005)
 - Since 2008, known as “Return Oriented Programming”
- Meta-data corruption
 - “Smashing C++ VPTRs” (Eric Landuyt, 2000)
 - “V00d00 malloc tricks” (Michel Kaempf, 2001)
 - Many, many other papers.

Today's exploits techniques (2)

- Information disclosure attacks
 - Format bugs (tf8 wu-ftpd 2.6 site-exec exploit, ~ 2000)
 - Weaknesses where content or address of target variables/functions can be read (BIND TSIG Exploit by LSD-PL, Openssl-too-open exploit by Sotirov, ~ 2001)
 - “Return into printf/send” (“Bypassing PaX ASLR protection”, Vanegue 2002)
- Heap chunks alignment techniques
 - “Advanced DL malloc exploit” (JP @ core-st , 2003)
 - “Heap Feng Shui”, (Sotirov, 2007)
- JIT attacks : make target generate “chosen” new code
 - “Pointer inference and JIT spraying” (Blazakis, 2010)

Exploit Mitigations

- Data Execution Prevention (DEP/Openwall/PaX/W^X/etc)
- Address Space Layout Randomization (ASLR)
- Control-Flow Integrity (CFI)
- Intra-modular displacement randomization (IDR)
- Heap randomization (non-deterministic fitness algorithms)
- Many others targeted protections (UDEREF, SEHOP, canary insertion, meta-data encoding, etc)

Full AE Models: The Automated Exploitation (AE) problem is solved if mitigations can be bypassed using minimal to no human interaction.

Restricted AE Models: Academic exercise where mitigations are ignored. Not the subject of this talk.

Control Flow Integrity

- Early implementation by Determina called “Program Shepherding” early 2000. Formalized by Martin Abadi et al. in 2005. A lot of work done at Microsoft, Intel, and more to make it practical – its hard.
- In a nutshell (idealized) :
 - Enforce strict transitions on the control flow graph, in particular between functions.
 - If $A \rightarrow B$ and $B \text{--ret}\rightarrow A$, then $A \rightarrow C$ is forbidden, so is $B \text{--ret}\rightarrow D$ (for C and D any other two functions)
- Consequence: Exploit cannot easily corrupt a function pointer or a return address and execute a ROP payload.

Intra-modular Displacement Randomization

- [Miller, Johnson, Goel, Vanegue, 2011] at Microsoft Security. (<http://ip.com/IPCOM/000210875>)
- Core idea: randomize address space not only using module base address randomization, but also within a module (ex: between functions).
 - Ability to change function relative address from the base address every time a program is executed.
- Consequences:
 - Base address information disclosure is not enough to predict addresses of ALL gadgets in a module.
 - Attacker worst case: need one information disclosure per randomization point inserted in the module.

Exploit primitives

- Two major families of exploit primitives are write primitives (write address space) and read primitives (read address space).
- Early classification done by Gerardo Richarte at core-st : “About exploit writing”, 2002.
- Modern classification done by Matt Miller: “Modeling the exploitation and mitigation of memory safety vulnerabilities”, 2012.

Exploit write primitive

General form: $*(\text{basepointer} + \text{offset}) = \text{value}$

(1) Base, offset and values are attacker-controlled

→ Write controlled value at controlled location

(2) Base and offset are controlled

→ Write uncontrolled value at controlled relative location

→ With an information disclosure, can always be used to uncover new state space or elevate privileges

(3) Only RHS Value is controlled (totally or partially)

→ Write anything at fixed location

→ Can be useful if value is:

- Later used as base pointer, index, or offset (we fall into case 1 or 2)
- Used in a control predicate and can uncover new “weird” state space
- Controlling privilege level of application

Exploit read primitive

General form: $\text{value} = *(\text{basepointer} + \text{offset})$

(1) Base, offset and values are attacker-controlled

→ Read value at desired location and store it at desired location

(2) Base and offset are controlled

→ Read value at desired location, store it at uncontrolled location

→ Only useful if uncontrolled location can be read by attacker

(3) Only LHS Value is controlled

→ Read internal program value and store it at desired location

→ Can be useful if value is:

- Internal program value is a direct code or data address
- Internal program value contains credentials (password, key, token, etc)
- Internal program value help deduce useful address info or credentials

Rising exploit techniques

- Data-only attacks (DOA)
 - Change internal program values to elevate privileges without changing Program control flow.
 - Infer address of data in program without direct memory read primitives.
- Program Likelihood Inference (PLI)
 - Probabilistic attacks: discover most likely executions to successful exploitation in non-deterministic environment.
 - Timing attacks: discover internal program information via run time execution measurements.

Tools Armory

Exploit Generation

- Automated Exploitation focuses on discovery and combination of write primitives and read primitives.
- Automated Exploitation in Full Model is a very hard problem. Anybody telling you otherwise is a fool or an impostor.
- Existing AE work focused on Restricted Models:
 - Sean Heelan’s “Automatic Generation of Control Flow Hijacking Exploits for Software Vulnerabilities” :
<http://www.cprover.org/dissertations/thesis-Heelan.pdf>
 - David Brumley et al. (AEG, MAYHEM, etc)
<http://users.ece.cmu.edu/~dbrumley/pubs.html>

Analysis and Exploit Automation

- Compilers (Program transformation)
- Fuzz testers (Input generation)
- SMT solvers (Symbolic reasoning)
- Model Checkers (State space exploration)
- Symbolic Execution Eng (Path generation)
- Emulators (Machine modeling)
- Abstract interpreters (Abstraction)

SMT solvers

SMT = Satisfiability Modulo Theories

- Give it a list of variables and constraints on them, will tell you whether the set of constraints is satisfiable.
- A good representation to reason about a program (e.g. translate a program into an SMT formulae)
- Can track feasibility of predicates, eliminate impossible program paths, etc.

EXAMPLE 1: $(B \geq A) \ \&\& \ (A \leq B)$ is SAT

EXAMPLE 2: $A \ \&\& \ B \ \&\& \ \text{NOT}(A\&\&B)$ is UNSAT

An open-source SMT solver : Z3

- Z3 is a state-of-the-art SMT solver developed in Microsoft Research RiSE group.
- Understand equalities, arrays, bitvectors, uninterpreted functions, and custom theories.
- Makes SMT a good symbolic representation to reason about programs (e.g. by translating it into SMT formulae).

Try by yourself on <http://rise4fun.com/Z3/>

Example of translation from C to SMT

```
F(int c)
{
  int ret;
  if (c < 10)
    ret = 1;
  else
    ret = 2;
}

(declare-fun x () Int)
(declare-const ret Int)
(declare-const c Int)
(assert (=> (>= c 10) (= ret 2)))
(assert (=> (< c 10) (= ret 1)))
(assert (= ret 1)) // check me!
(check-sat)
(get-model)
```

Output model for constraint set

- A model is a valuation of the variables for which a (SMT) formula is true.
- In this example, the constraints set is satisfiable if variable $C = 9$ and $RET = 1$
- Change the last assertion of previous slide and see what happens to the model.

Z3 output:

```
sat (model  
  (define-fun c () Int 9)  
  (define-fun ret () Int 1) )
```

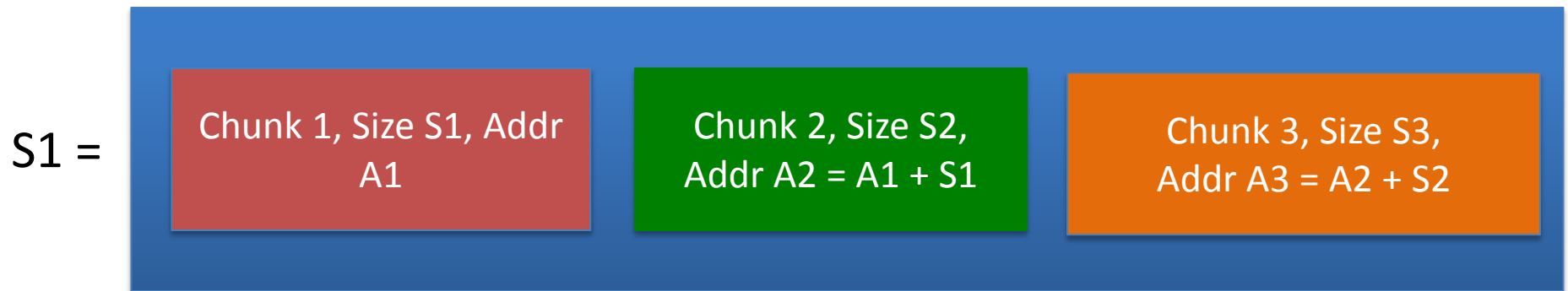
HAVOC: static analysis for C/C++

- HAVOC: Verifier for C(++) programs
<http://research.microsoft.com/en-us/projects/havoc/>
- Translate C/C++ code to Boogie IR
(Open source at: <http://boogie.codeplex.com>)
- Boogie IR is then translated to SMT formulae understood by Z3, which performs SMT check and give you a model.
- At Microsoft, HAVOC found 100+ security vulnerabilities in Windows and Internet Explorer.
- Experiments documented in: “Towards practical reactive security audit using extended static checkers”
<http://research.microsoft.com/pubs/185784/paper.pdf>

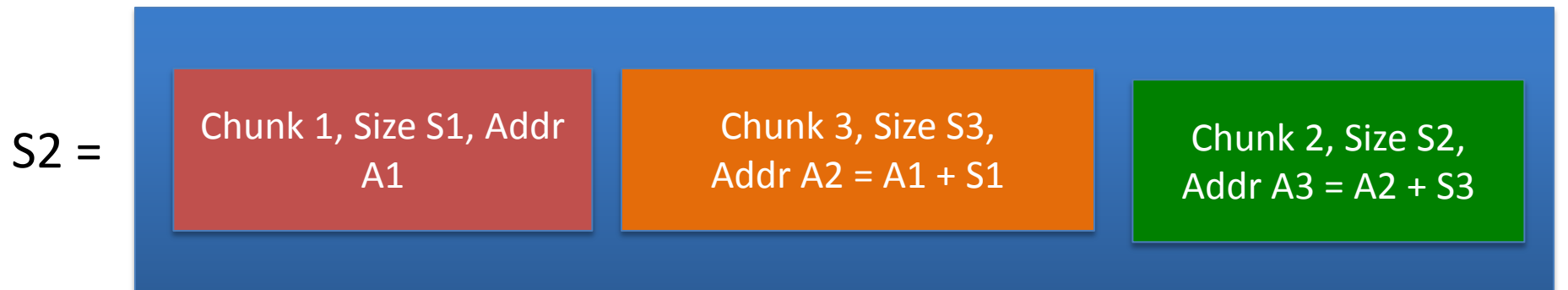
Problem: non-deterministic programs

Assume an attacker can overflow chunk 1 and chunk 3 is a target:

Heap in 90% of executions of program P :



Heap in 10% of executions of program P :



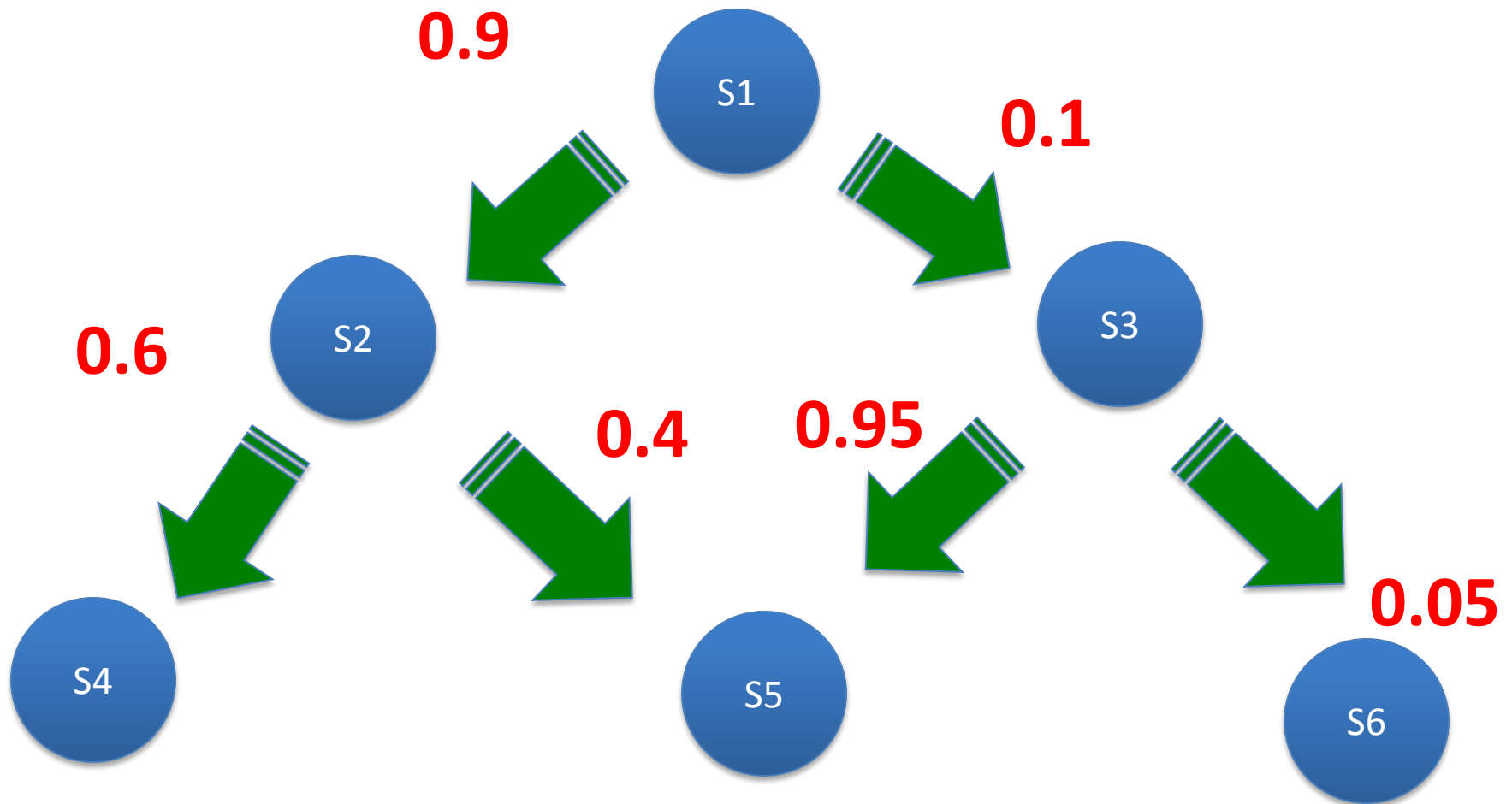
SMT solvers are unable to reason about non-determinism

Idea: Markov exploits



- Andrei Markov (1856-1922)
- Systems (Programs) may seem to act randomly, but have a hidden probabilistic regularity.
- Instrument program and deduce from sampling which paths have most chance to bring the heap in a desired exploitable state.

Markov transition system



The transition system model the set of all possible random walks.

Markov transition system

Previous slide explained:

- We computed the probability of reaching every heap states in a maximum of two heap interactions (malloc, free, etc)
- Probability of reaching S4 is:
$$P(S4) = P(S4 | S2) * P(S2 | S1) = 0.6 * 0.9 = 0.54 \text{ (54\%)}$$
- Probability of reaching S5 is:
$$P(S5) = P(S5 | S2) * P(S2 | S1) + P(S5 | S3) * P(S3 | S1)$$
$$= 0.9 * 0.4 + 0.95 * 0.1 = 0.455 \text{ (45.5\%)}$$
- Probability of reaching S6 is:
$$P(S6) = P(S6 | S3) * P(S3 | S1) = 0.1 * 0.05 = 0.005 \text{ (0.5\%)}$$

Assuming S5 and S6 are the only two desired exploitable states, the most exploitable random walk ends in S5.

Markov Exploit Food for thoughts

- Paths exploration strategy can be static or dynamic (planned, or constructed on the fly)
- If one creates an accurate heap manager specification, heap state measurement could be static, but this is a very hard and allocator-dependent task.
- Most likely, one needs to execute program and instrument debugger to measure heap state when heap operations are performed.
- After monitoring, one can construct the Markov transition system based on sampled program paths. More samples means heap model is more accurate.

Markov Exploit Food for thoughts (2)

- Determine list of possible heap interactions (malloc, free, etc) sequences in a given program. A single unique sequence may be represented by multiple random walks due to non-deterministic heap manager behavior.
- Determine sequence maximizing probability of reaching desired heap state in a minimum amount of steps. A SMT solver can be used to craft corresponding input based on encountered path predicates.
- A range of Markov models can be used to facilitate encoding of heap structure into a probabilistic transition system (Markov chain, Markov network, etc)

Challenge problems



Hilbert's program

- In 1900, German mathematician David Hilbert formulates a list of 23 hard problems touching the foundations of mathematics. Five of these problems remain unsolved today.

http://en.wikipedia.org/wiki/Hilbert's_program

A Program for Automated Exploitation

- Inspired by David Hilbert and many ones after him, we define a list of problems whose solutions pave the way for years to come in the realm of software security and exploitation.
- The Grand Challenge consists of a set of 11 problems in the area of vulnerability discovery and exploitation that vary in scope and applicability.
- Most problems relate to discovering and combining exploit primitives to achieve elevation of privilege.

Exploit challenges are not new

- Gerardo Richarte's insecure programming (from 10 years ago!) constitutes great training for manual exploit writing:

<http://community.coresecurity.com/~gera/InsecureProgramming/>

- Many of the “Capture the Flag” events are, in essence, manual exploit challenges.
- In this challenge, we expect exploits to be generated automatically instead of written manually.

Nature of Grand Challenge problems

- Exploit Specification problem (A, H)
- Input generation problems (B, C, D, E)
- Exploit Primitive composition problem (F)
- Environment determination (I, J, K)
- State space representation (G)

Not all problems need to be resolved for a given target as different problems cover different exploit scenarios.

Grand Challenge Evaluation

Two main problems of Automated Exploitation are **Vulnerability Discovery** and **Vulnerability Exploitation**. Solutions to challenge problems must be evaluated on their varying degree of:

- Soundness (Precision and Signal/Noise ratio)
- Expressivity (Applicable domain and Configurability)
- Scalability (Automation and Performance)
- Completeness (Coverage)
- Resilience (to Environment and Exploit Mitigations)

Exploit specification

Problem A: Given a program P , determine the set of assertions S for which satisfying any a in S is equivalent to corrupting the program.

In other words, what is the program P
anti-specification ?

Problem A code

```
F(int x, int y)
{
    int loc[4];
    int idx = G(x, y);
    if (idx > 4)
        return -1;
    assert(idx >= sizeof(loc)); // do infer assertion
    loc[idx] = 0x00;
}
```

Pre/post-conditions inference

Problem B: Given a program function and an assertion in the function, determine the necessary and sufficient pre/post conditions such as the assertion is true if and only if the pre/post conditions is true.

This is equivalent to the input generation problem for loop-free programs.

Note: May need to walk over call graph to resolve problem transitively from entry point to assertion.

Problem B code

PRECOND (?)

F(int x, int y)

{

int array[4];

int idx = G(x + y);

assert(idx >= 4);

array[idx] = 0;

}

PRECOND (?)

Int G(int x, int y)

{

if (x < y) return x;

else return 0;

}

POSTCOND (?)

Problem B code

PRECOND (?)

F(int x, int y)

{

int array[4];

int idx = G(x + y);

assert(idx >= 4);

array[idx] = 0;

}



PRECOND (?)

Int G(int x, int y)

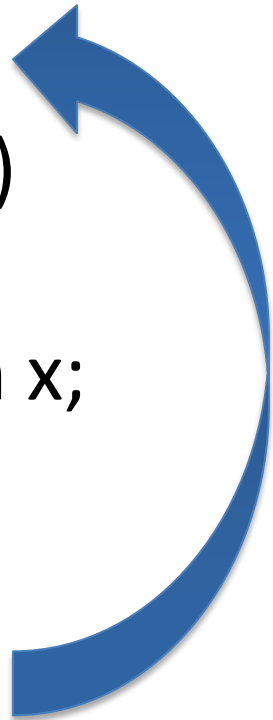
{

if (x < y) return x;

else return 0;

}

POSTCOND (?)



Loop contract inference

Problem C: Given a program loop and an assertion $A1$ within or at the loop exit-node, determine loop-contract assertion $A2$ such as $A1$ is true if and only if $A2$ is true.

Note: A loop invariant is an assertion that must be verified at every iteration of the loop. Given that we work on a program anti-specification, the desired exploit loop contract is not necessarily a loop invariant (it could just be true at some iterations).

Problem C code

```
F(char *buf, int bufsz)
{
    int limit = bufsz;
    int idx = 0;
    loop_invariant(?)
    while (i < limit)
    {
        if (buf[i] == '{') limit++;
        else if (buf[i] == '}') limit--;
        i++;
    }
    assert(i >= sizeof(buf));
    buf[i] = 0;
}
```



Exploit input definability

Problem D: Given an initial state I of a program P with functions and loops, exhibit an algorithm converging to a desired sink state.

A desired sink state can be defined as an assertion in the program (more weakly: as a set of chosen variables values).

Problem D code

```
F(int x, int y)
{
    int loc[4];
    int idx = G(x, y);
    if (idx > 4)
        return -1;
    while (x < y) idx++;
    assert(idx >= sizeof(loc)); // how to reach this?
    loc[idx] = 0x00;
}
```

Exploit derivability

Problem E: Given a concrete program input and associated program crash/log, find the longest crash trace prefix from which the desired exploitable program state can be reached.

The available program crash/log can be:

- (1) Full (unlimited access to all values ever)
- (2) Partial (only active values are tracked)
- (3) Control-only (ex: a stack or instructions trace)

Problem E code

```
F(int x, int y)
{
    int loc[4];
    if ((x + y) > sizeof(log))
        return (loc[x]);           // program crash here
    else if ((x + y) <= sizeof(loc)) {
        x = G(x, y);
        loc[x] = 0;                // how to reach here?
        return (0);
    }
}
```

```
Int G(int x, int y) { while (x < y) x++; return (x); }
```

Multi-interaction exploit

Problem F: Given a program initial state I , a desired program state U unreachable from I within any single program interaction R , determine all intermediate states T such as multiple interactions R_i can be composed to reach U as in : $R_1(I,T) + R_2(T,U)$

Transitive decomposition: determine minimum number of interactions to reach U from I .

Problem F code

```
Char *glob;
F(int x, int y)           // Ex: F and G are syscalls
{
    glob = malloc(x + y); // integer overflow
}
G()
{
    glob[x] = 0;          // array OOB access
}
```

How to construct Trigger() = { F(); G(); } ?

Minimal concurrent exploit

Problem G: Given a program P , a desired exploit state S , and a thread count C , find the minimal state space representation to reach S in some execution of P **while retaining ability to generate corresponding concrete input.**

Note 1: Partial Order Reduction is a generic framework that can help control state space explosion.

Note 2: Minimal state space representation is dependent on desired sink state (as in Abstract Interpretation).

Example of research in this area: “Identifying and Exploiting Windows Kernel Race Conditions via Memory Access Patterns” (Jurczyk / Coldwind, 2013)

Problem G code

```
/* Example of basic TOC/TOU vulnerability */  
/* ptr holds a valid non-volatile pointer */  
F(unsigned int *ptr)  
{  
    if (*ptr > 0x10) return;  
    global->ptr = malloc(*ptr + 1);  
    if (global->ptr == NULL) return;  
    global->ptr[*ptr] = 0x00;    // double-fetch!  
}
```

If *ptr* is “modified under” by another thread, the second array access can go OOB.

Privilege Separation Inference

Problem H: Given a program P, determine code privilege partitioning. For each partition, determine entry points.

- (1) Determine variables guarding privilege level (PL)
- (2) Partition functions so that all elements of a given partition share the same PL. If static partitioning does not exist, determine parameters of dynamic partitioning.

Partitioning can determine multi-stage exploits paths:

- Remote → Local → Kernel
- Remote → Sandboxed → Unsandboxed
- Remote → Non-authenticated → Authenticated

Problem H code

```
bool authenticated = false;
Int F()
{
    authenticated = check_creds();
    // execute at authenticated level
    if (authenticated)
    {
        bool res = serve_client();
        if (!res) return (send_error(E_FUNC));
        return (0);
    }
    // execute at non-authenticated level
    return (send_error(E_AUTH));
}
```

Note: send_error() can execute at multiple privilege levels.

Heap likelihood inference

Problem I: Given a program P using a non-deterministic heap allocator, determine most exploitable random walk(s) for P to reach “aligned” exploitable heap state.

- (1) Assume existence of heap corruption C in P
- (2) Identify set S of exploitable heap states w.r.t. C
- (3) Minimize steps to reach any element of S

See previous Markov exploit description. This problem is more relevant in presence of heap randomization.

Problem I code

```
Struct s1 { int *ptr; } *s1a = NULL, *s1b = NULL, *s1c = NULL;
```

```
Struct s2 { int authenticated; } *s2 = NULL;
```

```
F() {
```

```
    s1a = (struct s1*) malloc(sizeof(struct s1));
```

```
    s1b = (struct s1*) malloc(sizeof(struct s1));
```

```
    s1c = (struct s1*) malloc(sizeof(struct s1));
```

```
}
```

```
G() { s2 = (struct s2*) malloc(sizeof(struct s2)); }
```

```
H() { free(s1b); }
```

```
I() { memset(s1a, 0x01, 32); }
```

```
J() { if (s1 && s1->authenticated) puts("you win"); } // Print this
```

```
K() { if (s2 && s2->ptr) *(s2->ptr) = 0x42; } // Avoid crash here
```

When allocator reuses s1b's memory to allocate s2 :

Automate best walk = { F(); H(); G(); I(); J(); }

Generalized program timing attack

Problem J: Define the necessary and sufficient execution time analysis conditions to infer value, size, or location of:

(1) A program control structure

– Return address, Function Pointer, Exception Handler, etc.

(2) A program data structure

– Heap chunk, Stack Frame, Global variable, etc.

(3) A program code fragment

– Instruction, Function, Method, etc.

In other words, automate program time inference to defeat stack and heap randomization.

Problem J examples

The problem is stated in very generic terms on purpose.

Resolution depends on target-specific implementation.

For two great starting point on timing inference, see:

Cryptographic timing attacks on DH, RSA, DSS and other systems
(Paul C. Kocher, 1996)

<http://www.cryptography.com/public/pdf/TimingAttacks.pdf>

Program timing attacks on Firefox hash tables

(Paul @pa_kt, 2012)

<http://gdtr.wordpress.com/2012/08/07/leaking-information-with-timing-attacks-on-hashtables-part-1/>

Indirect information disclosures

Problem K: Define the necessary and sufficient conditions to infer the value or address of a variable without a direct read primitive, such as:

(1) Data reuse attacks

(example: partial pointer overrides)

(2) Pointer value prediction attacks

(example: pointer inference)

Problem K examples

Resolution of Problem K depends on target-specific implementation.

Prior art on Indirect information disclosures includes:

Flash Pointer Inference (Blazakis, 2010)

<http://www.semanticscope.com/research/BHDC2010/BHDC-2010-Paper.pdf>

Garbage Collection marking attack (Blazakis, 2013)

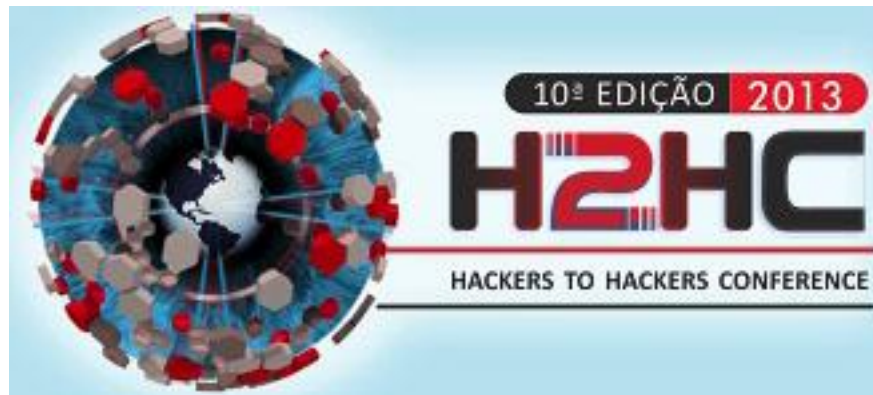
<http://www.trapbit.com/talks/Summerc0n2013-GCWoah.pdf>

Conclusion

- We decomposed the problem of Automated Exploit Generation in a set of challenges with clear intermediate assumptions.
- Resolving one such sub-problem is a step towards existing end-to-end solutions of larger and larger sub-classes of exploits.
- Even though Automated Exploitation is an undecidable problem, observing that most vulnerabilities are shallow allow the problem to be approached.

Questions / Discussion

- Thanks for attending H2HC 10th anniversary



- Questions and feedback welcome by email